

# Emergence of geometry in stochastic systems

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**motivation**  $\exists$  analogies between quantum systems and stochastic systems [Nelson(1966), Parisi,Wu(1981)]

→ Can quantum gravity be formulated by using stochastic processes?

**main results** [We here focus on Markov chains as stochastic processes.]

- For a given Markov chain, we introduce **a geometry in configuration space** by defining **the distance between configurations**.
- We show that **AdS geometry emerges** for the **simulated tempering algorithm**. [Marinari,Parisi(1992)]  
[we can **optimize parameters in numerical simulations geometrically**. (← practical use of the distance)]

## (A) Definition of the distance

• We first prepare some quantities to define the distance:

•  $\mathcal{M} \equiv \{x\}$ : configuration space,  $S(x)$ : action

• Markov chain with a transition matrix  $P(x|y)$  ( $\equiv \langle x|\hat{P}|y\rangle$ ):

$$x_0 \xrightarrow{\hat{P}} x_1 \xrightarrow{\hat{P}} x_2 \xrightarrow{\hat{P}} \dots$$

Probability distribution after  $n$  steps:  $P_n(x|x_0) \equiv \langle x|\hat{P}^n|x_0\rangle$

• Assumptions on  $\hat{P}$ :

- ① unique convergence:  $P_n(x|x_0) \xrightarrow{n \rightarrow \infty} \frac{e^{-S(x)}}{Z}$  ( $\forall x_0$ ) [ $Z \equiv \int dx e^{-S(x)}$ ]
- ② detailed balance:  $P(x|y)e^{-S(y)} = P(y|x)e^{-S(x)}$
- ③ eigenvalues are all positive

• Transfer matrix:  $\hat{T} \equiv e^{S(\hat{x})/2} \hat{P} e^{-S(\hat{x})/2}$

$\hat{T}$  is positive and symmetric (due to ③ and ② above).

Spectral decomposition of  $\hat{T}$ :

$$\hat{T} = |0\rangle\langle 0| + \sum_{k \geq 1} \lambda_k |k\rangle\langle k| \quad \left[ \langle x|0\rangle = \sqrt{\frac{e^{-S(x)}}{Z}} \right] \quad [1 > \lambda_1 \geq \lambda_2 \geq \dots]$$

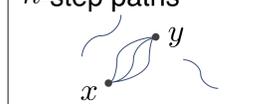
Relaxation to the equilibrium can be understood as the decoupling of higher modes:  $\hat{T}^n \xrightarrow{n \rightarrow \infty} |0\rangle\langle 0|$ .

• Connectivity  $f_n(x, y)$ :

$f_n(x, y) \equiv$  [probability to find a path connecting  $x$  and  $y$  in the set of  $n$ -step paths in equilibrium]

$$= P_n(x|y) \cdot \frac{e^{-S(y)}}{Z}$$

$n$ -step paths



Normalized connectivity  $F_n(x, y)$ :

$$F_n(x, y) \equiv \frac{f_n(x, y)}{\sqrt{f_n(x, x)f_n(y, y)}} = \frac{\langle x|\hat{T}^n|y\rangle}{\sqrt{\langle x|\hat{T}^n|x\rangle\langle y|\hat{T}^n|y\rangle}}$$

**Notes**

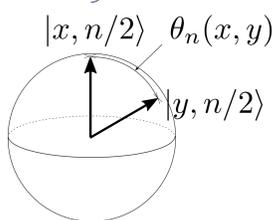
◦  $F_n(x, x) = 1$

◦ With normalized states  $|x, n/2\rangle \equiv \frac{\hat{T}^{n/2}|x\rangle}{\|\hat{T}^{n/2}|x\rangle\|}$ ,  
 $F_n(x, y) = \langle x, n/2|y, n/2\rangle$ .

• We define the distance by

$$\theta_n(x, y) \equiv \arccos F_n(x, y)$$

$\theta_n(x, y)$  is actually an inner angle between the normalized states  $|x, n/2\rangle, |y, n/2\rangle$ .



### Basic properties

- $\theta_n(x, y)$  satisfies the axioms of distance.
- If  $x$  can be easily reached from  $y$ ,  $\theta_n(x, y)$  is small.
- $\theta_n(x, y) \xrightarrow{n \rightarrow \infty} 0$  [ $\forall x, y$ ]

• Instead of  $\theta_n(x, y)$  we can also use:

$$d_n(x, y) \equiv \sqrt{-2 \ln F_n(x, y)} \quad \leftarrow \text{we use this in the following}$$

• Universality of distance

**Statement**

There are many algorithms to construct  $\hat{P}$  satisfying ①-③ above. Among them, for a class of algorithms which generate local moves in configuration space,

**large scale behavior of  $d_n(x, y)$  does not depend on the details of the algorithms.**

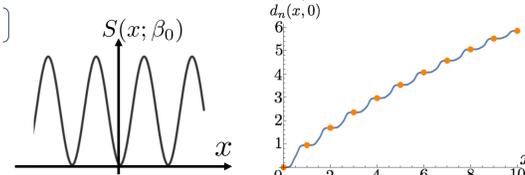
• Examples

• **quadratic action**:  $S(x) = \frac{\omega}{2} x^2$

analytic form of the distance:  $d_n(x, y) = \sqrt{\frac{\omega}{2 \sinh(\omega t)}} |x - y|$   
(using the Langevin algorithm)

• **cosine action**:  $S(x; \beta_0) = \beta_0 \sum_{\mu=1}^D (1 - \cos(2\pi x_\mu))$  ----- (\*)

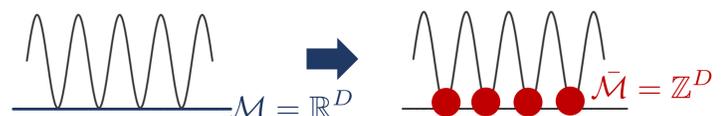
[ $D = 1$ ]



• To investigate the large scale geometry of the configuration space, we **coarse-grain** the configuration space.

(identify configurations in the same mode as a single configuration)

e.g. for the cosine action (\*)



$d_n(x, y)$  does satisfy the triangle inequality after coarse-graining.

• Metric on  $\bar{\mathcal{M}}$ :

$$ds^2 \equiv d_n^2(x, x + dx) = \sum_{\mu, \nu} g_{\mu\nu}(x) dx_\mu dx_\nu. \quad (x, x + dx : \text{nearby points in } \bar{\mathcal{M}})$$

## (B) Emergence of AdS geometry

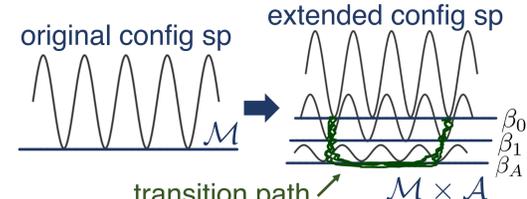
• We consider a system with highly multimodal equilibrium distribution and with highly degenerate vacua. (typical action: the cosine action (\*)

• We implement the **simulated tempering algorithm**:

(an algorithm to accelerate relaxation [Marinari,Parisi(1992)])

• We extend the configuration space from  $\mathcal{M}$  to  $\mathcal{M} \times \mathcal{A} \equiv \{x, \beta_a\}$ .

[ $\beta_a$ : the overall coefficient of the action]  
[ $\beta_0$ (original value)  $> \beta_1 > \dots > \beta_A$ ]

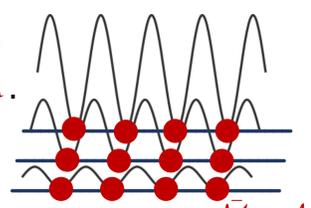


different modes are now connected in the small  $\beta_a$  region

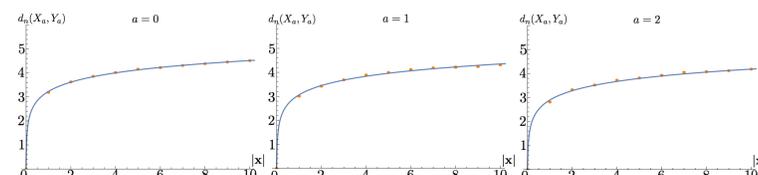
• To investigate the large scale geometry, we introduce **extended, coarse-grained configuration space  $\bar{\mathcal{M}} \times \mathcal{A}$** .

• One can show that the metric on  $\bar{\mathcal{M}} \times \mathcal{A}$  is AdS:

$$ds^2 = l^2 \left( \frac{d\beta^2}{\beta^2} + \alpha \beta^q \sum_{\mu=1}^D dx_\mu^2 \right)$$



numerical verification



• : numerical result of  $d_n(x, y)$   
— : analytic geodesic distance with parameters  
[ $l = 0.0404$   
 $\alpha = 2.34 \times 10^5$   
 $q = 0.289$ ]

## (C) Geometrical optimization

• Knowing geometry, we can optimize parameters in numerical algorithms. e.g. the simulated tempering

• We optimize the functional form of  $\beta_a = \beta(a)$  in such a way that **the distances between different modes are minimized**.

This should correspond to the case in which **the metric in the  $\beta$  direction becomes flat** when  $a$  is used as a coordinate:

$$\frac{d\beta^2}{\beta^2} = \frac{\beta(a)^2}{\beta(a)^2} da^2 \equiv (\text{const.}) da^2$$

$$\therefore \beta_a = \beta_0 e^{-Ra} \quad (R : \text{const.})$$

numerical verification

