

Renormalization, Thermodynamics, and Feature Extraction of Machine Learning

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References: arXiv: 1801.07172 [hep-th], 1810.08179 [cond-mat]

Nov. 6, 2018 @ Nagoya Univ.

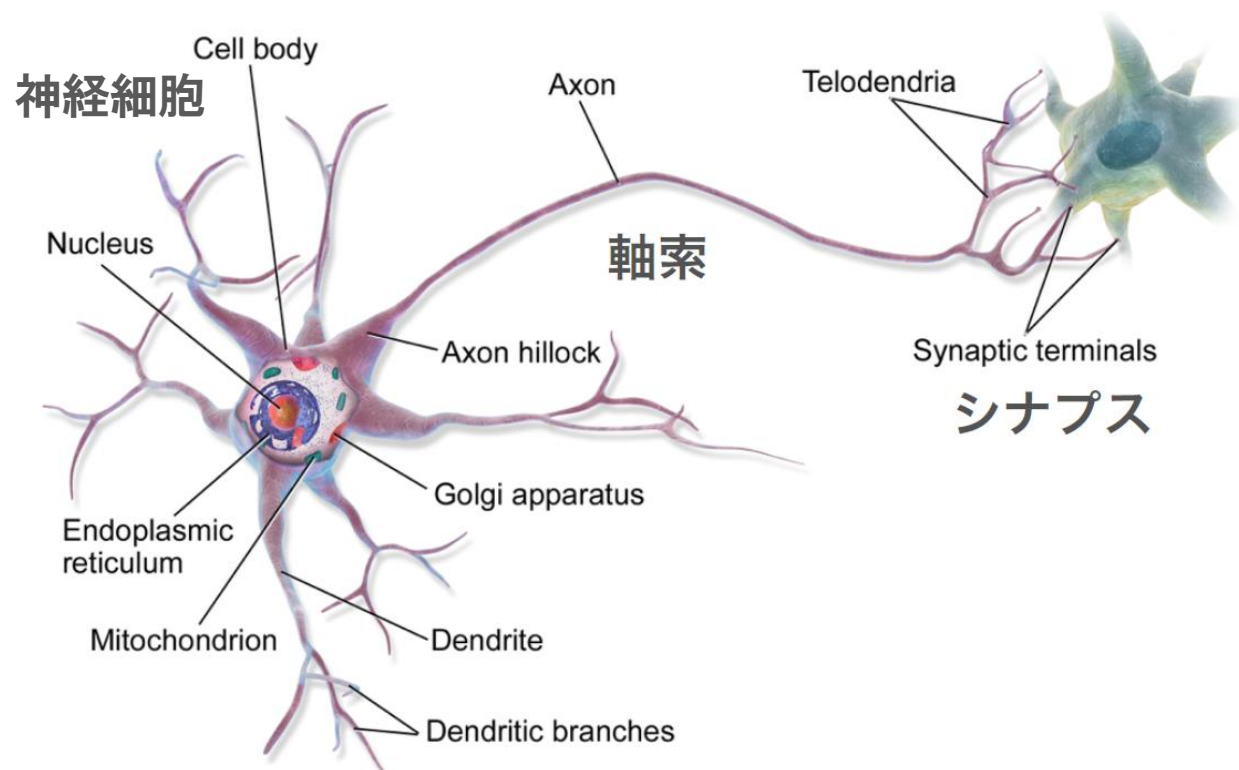
What is machine learning ?

- An attempt to reproduce actions of **consciousness** in a computer. There are two directions of research:
 1. By **teaching** a computer on various rules, we design a machine which can judge things like humans.
(e.g., Expert system)
 2. By emulating a **structure of human brain**, we design a machine which can **learn** and judge information.
→ **Machine learning** (ML)
- Both researches are ongoing now, but recently the latter has been greatly developed.

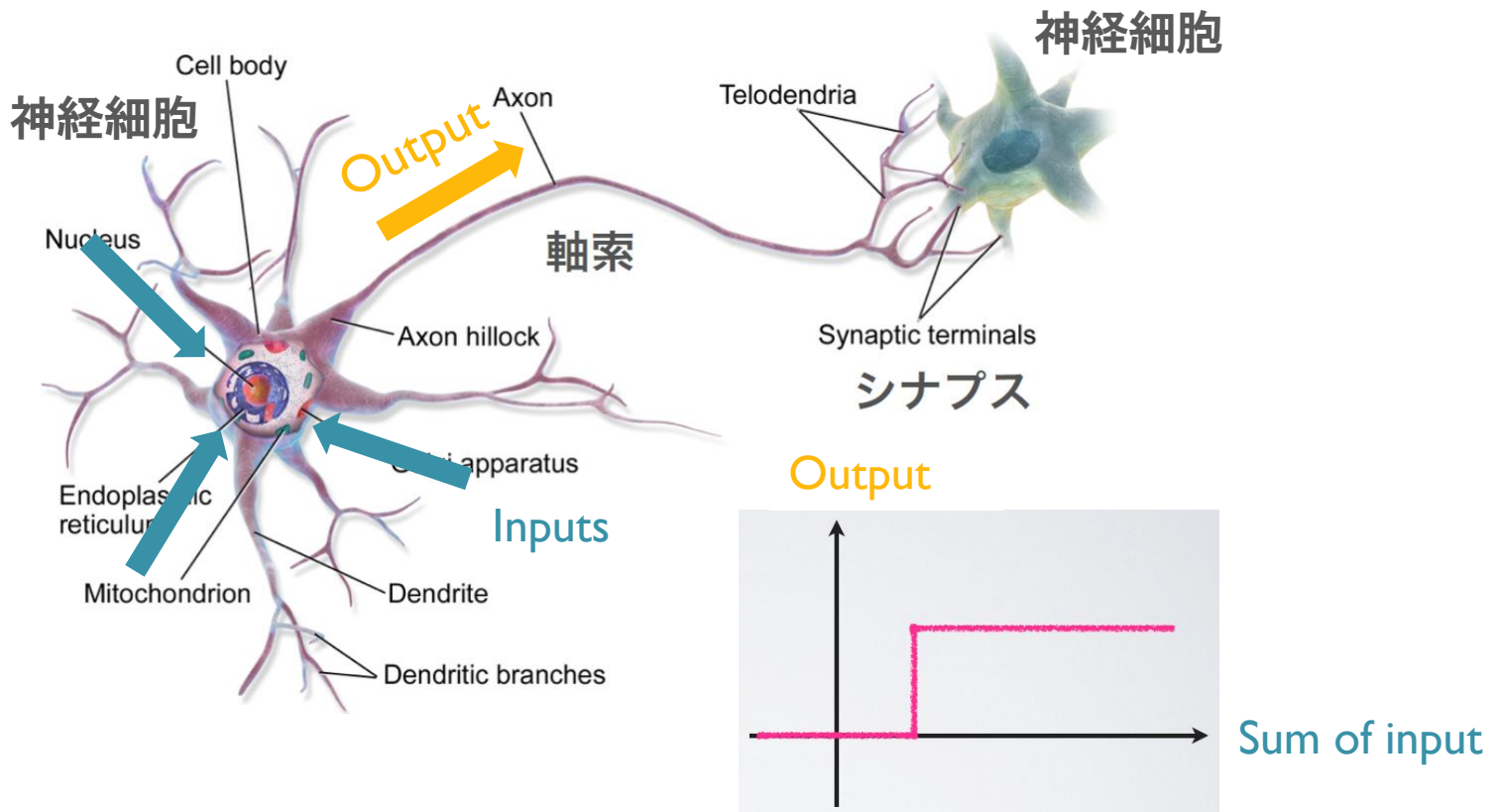
It finds
the rules!

Structure of human brain

- Human brain has about 100 billion **neurons** (神経細胞) and they are connected via **axons** (軸索) .

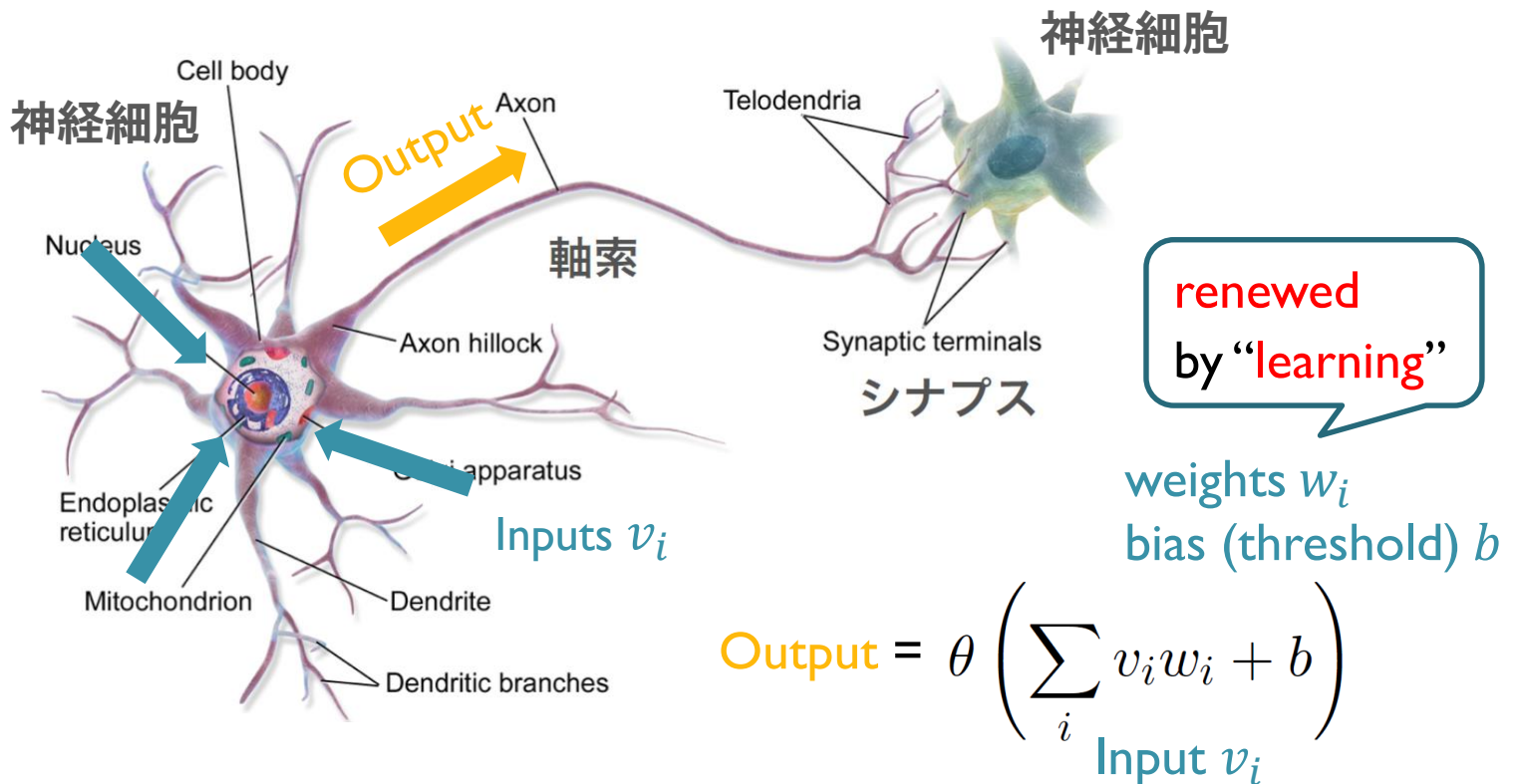


- A neuron receives electric **signals** sent from other neurons through axons.
- If a sum of input signal exceeds a **threshold**, the neuron fires and sends a signal to other connected neurons.



- Humans repeat trials and errors. After such experiences, our neurons renew a **way to exchange the signals** so that we can judge various things more properly.

→ This is nothing but **“learning.”**



Algorithm of machine learning

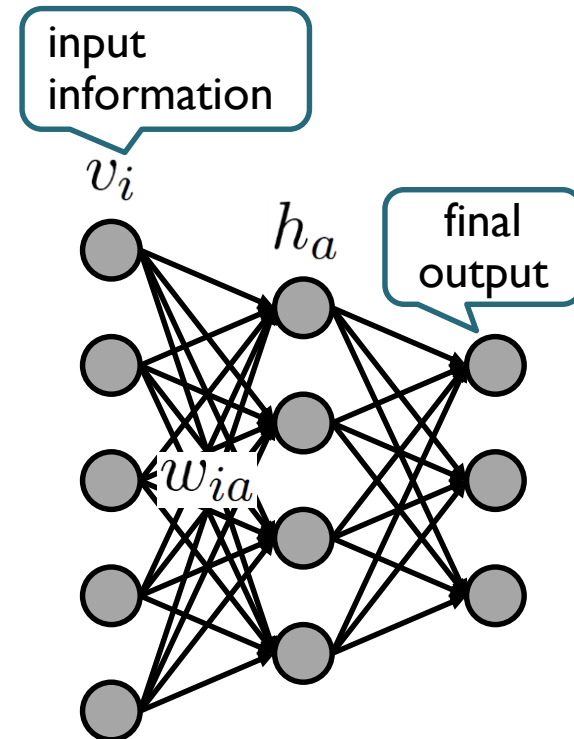
- By emulating a structure of brain, we make an algorithm of machine learning.
- We reproduce a network of neurons exchanging signals, such that

$$h_a = f \left(\sum_i v_i w_{ia} + b_a \right)$$

nonlinear function (**activation function**)

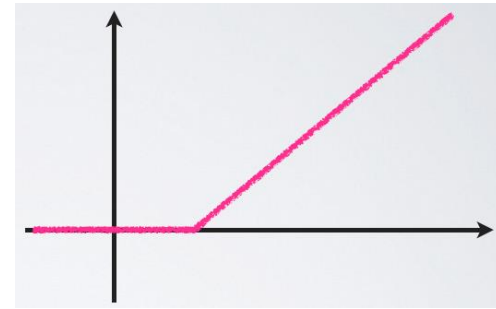
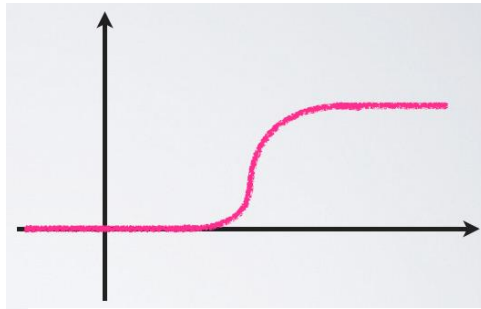
- We **adjust** weights w_{ia} and bias b_a so that the final output approaches desired values (answer) for us.

“training”



- As an **activation function**, we don't use step function but **sigmoid function** (left) or **ReLU** (right), because of analyticity.

tanh, too



$$f(x) = \frac{1}{1 + e^{-x}}, \quad f(x) = \begin{cases} x & \text{for } x \geq 0 \\ 0 & \text{for } x \leq 0 \end{cases}$$

- For the final output, the **softmax function** is often used, since we can interpret the output as **probability**.

$$g(x_i) = \frac{\exp x_i}{\sum_j \exp x_j}$$

- In order to **adjust** weights w_{ia} and bias $b_a \dots$
- We choose the **loss function** which evaluates difference between output at present and desired output.
Square sum or **relative entropy** is often chosen.

$$E = \frac{1}{2} \sum_n \left(v_L^{(n)} - y^{(n)} \right)^2$$

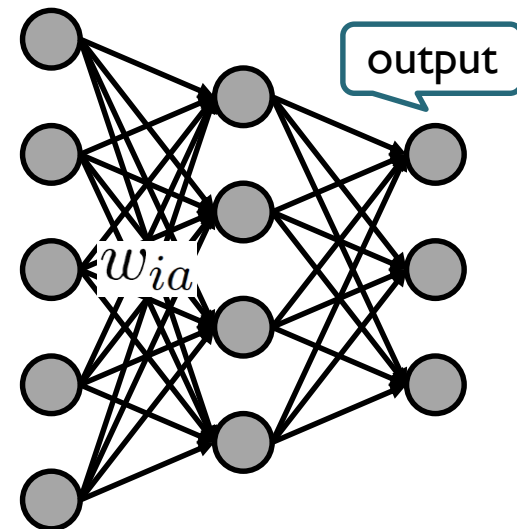
For probability distributions (later)

- Then we calculate weights and bias such that the loss function becomes the **minimum**.

Analytical calculation is *impossible*, since we can't solve nonlinear eqs with many variables.

- Instead, we use *numerical* calculations to find (practically) a **local minimum** by iterative approximation.

“training”



Google's cat (in 2012)

- Using such an algorithm, we can get interesting results.

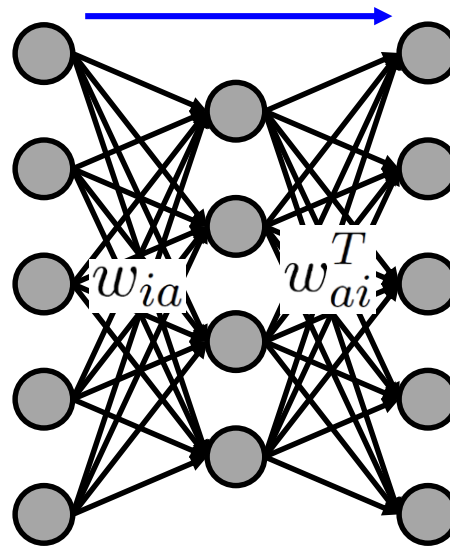
For example,

[Le et al., '12]



Input 10 million still images
clipped from YouTube movies.

each neuron for each pixel



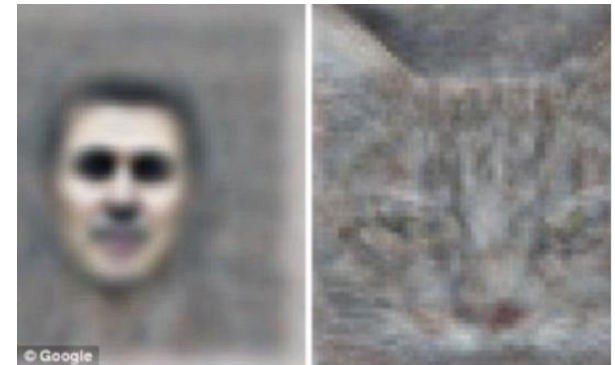
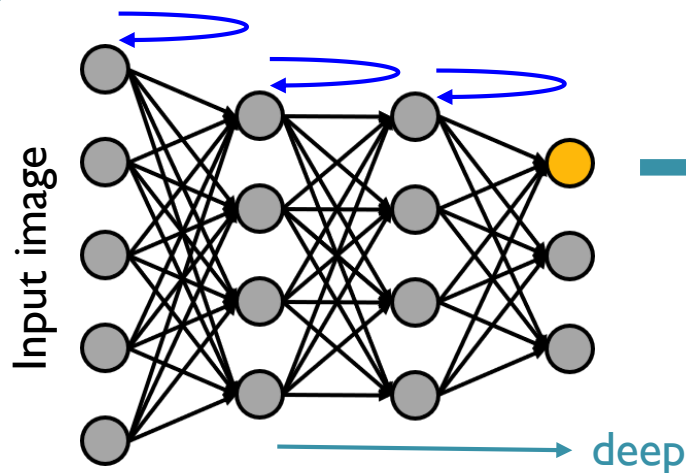
Desired output
= input itself
(autoencoder)

Humans don't
teach anything
but inputs!
(unsupervised)

A network of neurons (neural network, NN)

- What do the neurons learn?
 - If we make images which only a specific neuron react to, a **human** face or a **cat**'s face appears.
 - There are also neurons which react to simpler figures, such as a line, an edge or a triangle.
 - In general, neurons in **deep layer** react to **complicated** things. (We deepen a NN to combine many **autoencoders**.)
 - This may reproduce a human process of grasping "**features**."

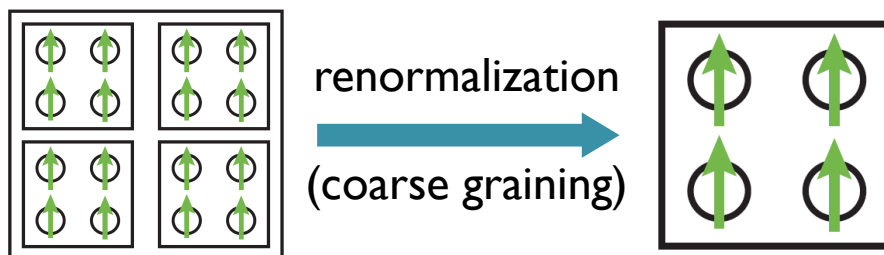
from large number of input data



- What does grasping “**features**” mean?
 - An image contains various information, but we extract an important part as its **features** and drop the other parts.
 - It is similar to the coarse graining, and then may be related to the **renormalization group** (RG).

iterative RG transformations

- Going along the RG flow, **relevant parameters** (~ features) are emphasized while irrelevant parameters are dropped.
- Let us discuss a relation of **feature extraction** in ML and **renormalization** in physics!



[Mehta-Schwab, '14]
 [Lin-Tegmark-Rolnick, '16]
 [Sato, '16]
 [Aoki-Kobayashi, '16]
 [Koch-Janusz, Ringel, '17]



Our experiments and results

Our experiment (I)

[Iso-SSF-Yokoo, '18]

[SSF-Giataganas, '18]



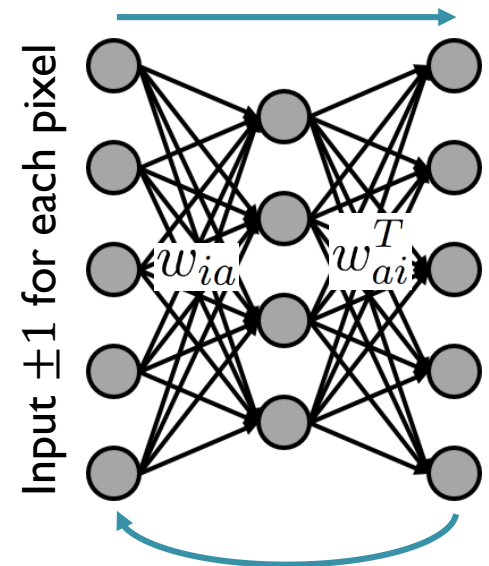
$T=2, H=0$



$T=6, H=0$

Relation to
RG flow?

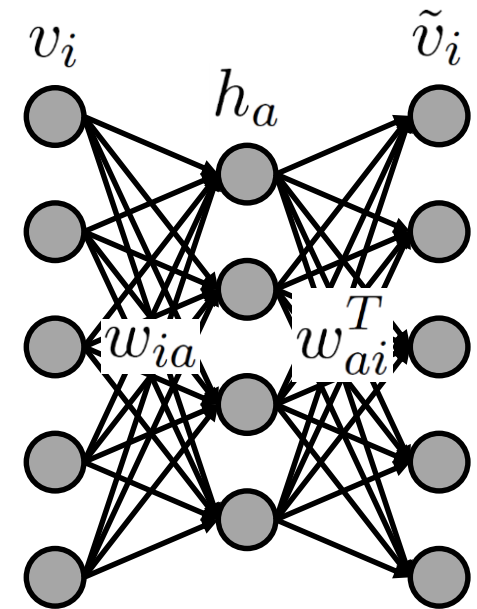
1. We generate **spin configurations** of Ising model (black-and-white images) using Monte Carlo simulation, since we know well about RG in Ising model.
2. We train a NN so that when we input the configs it outputs images **as similar as possible to inputs**. (Autoencoder, unsupervised learning)
3. After training (the weight is fixed), we input again the output configs. Doing this iteratively, we obtain the **flow** of configs.



Autoencoder (unsupervised learning)

- An autoencoder, which plays important roles in “Google’s cat,” is believed to extract “**features**” of input images.
- It can be related to the coarse graining: a NN **compresses** images and then **reconstructs** them.
- We train a NN so that it outputs the (ideally) same images as inputs with the **same probability**.
- This type of autoencoder is called **Restricted Boltzmann Machine (RBM)**.

Inputs contain configs
at various (T, H)



- The **probability** to output an image is defined, using the “**energy**” function

$$E(\{v_i\}, \{h_a\}) = \sum_{i,a} v_i w_{ia} h_a + \sum_a b_a h_a + \sum_i c_i v_i$$

Statistical physics

by **Boltzmann distribution**

weights w_{ia} , bias b_a, c_i

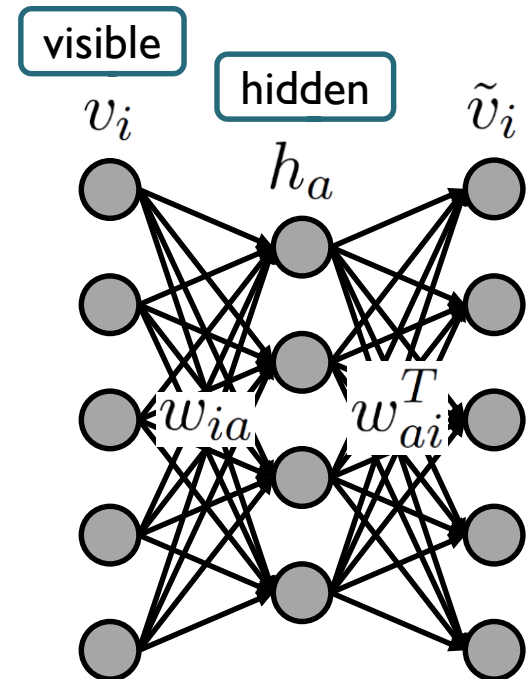
$$p(\{h_a\}) = \sum_{\{v_i\}} \frac{e^{-E(\{v_i\}, \{h_a\})}}{\mathcal{Z}}$$

$$\tilde{p}(\{\tilde{v}_i\}) = \sum_{\{h_a\}} \frac{e^{-E(\{\tilde{v}_i\}, \{h_a\})}}{\mathcal{Z}}$$

- We train the RBM (weights and bias) so that the **relative entropy** approaches a local minimum.

Distance between probability distributions

$$\sum_{\{v_i\}} q(\{v_i\}) \log \frac{q(\{v_i\})}{\tilde{p}(\{v_i\})}$$



- The relative entropy is also called **KL divergence**:

$$\sum_{\{v_i\}} q(\{v_i\}) \log \frac{q(\{v_i\})}{\tilde{p}(\{v_i\})}$$

prob of an input image = v_i / prob of an output image = v_i



- In our experiments, the **input images** are the spin configs in Ising model: $v_i = \pm 1$ for a white/black pixel.
- The expectation values of **outputs** are those of spins:

$$\langle h_a \rangle = \tanh \left(\sum_i v_i w_{ia} + b_a \right)$$

$$\langle \tilde{v}_i \rangle = \tanh \left(\sum_a h_a w_{ai}^T + c_i \right)$$

- The **final output** (reconstructed) images have spins $\tilde{v}_i = \pm 1$ by replacing an EV $\langle \tilde{v}_i \rangle$ with a probability $(1 \pm \langle \tilde{v}_i \rangle)/2$.

To keep
same EV

- The **probability distribution** of input configs $q(\{v_i\})$ and that of output configs $\tilde{p}(\{v_i\})$ are slightly different, even after the **training finished**.
(It's because the KL divergence cannot be zero, practically.)
- If we input again the output configs, we obtain another prob distribution $\tilde{\tilde{p}}(\{v_i\})$ of reconstructed configs.
- Doing this iteratively, we get the **flow** of prob distribution of spin configs: $q(\{v_i\}) \rightarrow \tilde{p}(\{v_i\}) \rightarrow \tilde{\tilde{p}}(\{v_i\}) \rightarrow \dots$

➤ Questions:

This is a well-defined question!

1. Does the “**RBM flow**” correspond to the **RG flow**?
2. Does it have the **fixed points** describing the “**features**”?
(The features are *emphasized* along the RBM flow.)

Our experiment (2)

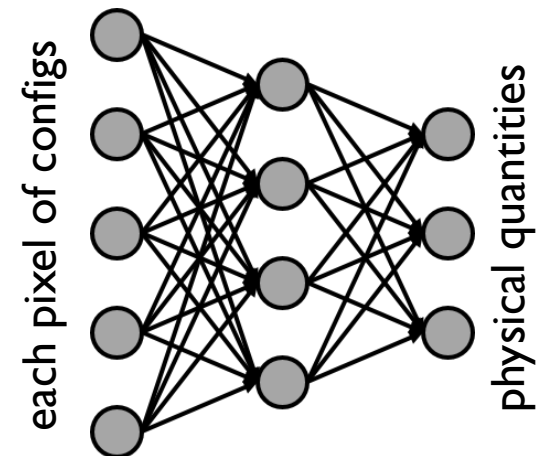
[Iso-SSF-Yokoo, '18]

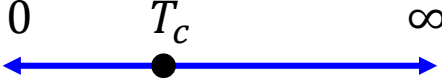
[SSF-Giataganas, '18]

- We check if the **RBM flow** is related to the **RG flow**.
- Let us translate the flow of spin configs into a **flow of physical quantities** (temperature T and magnetic field H), since it makes our discussion easier.
- To do this, we train *another* NN to output **correct values** of (T, H) of input configs. (**supervised learning**)

parameters when generated
by MC simulation

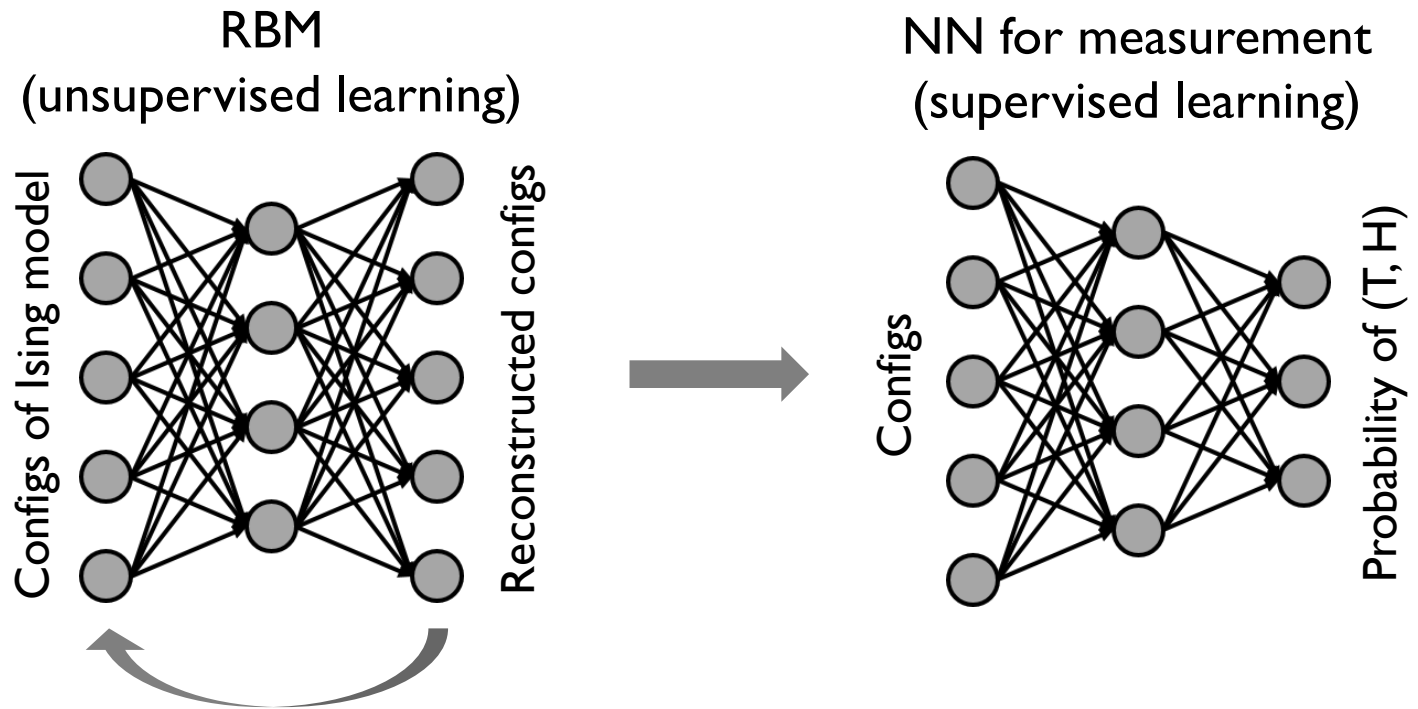
- Using this NN, we get a **flow of the physical quantities** $\phi = (T, H)$:
 $\phi(\{v_i\}) \rightarrow \tilde{\phi}(\{v_i\}) \rightarrow \tilde{\tilde{\phi}}(\{v_i\}) \rightarrow \dots$



- For example, in 2d Ising model (at $H=0$), 
- **RG flow** goes away from the **critical temperature** $T_c = 2.27$ and approaches to $T = 0, \infty$. Phase transition occurs
- If **RBM flow** behaves similarly, it should correspond to the RG flow (as we expected).

coupling
 $J = 1$ fixed

Summary of
our setup

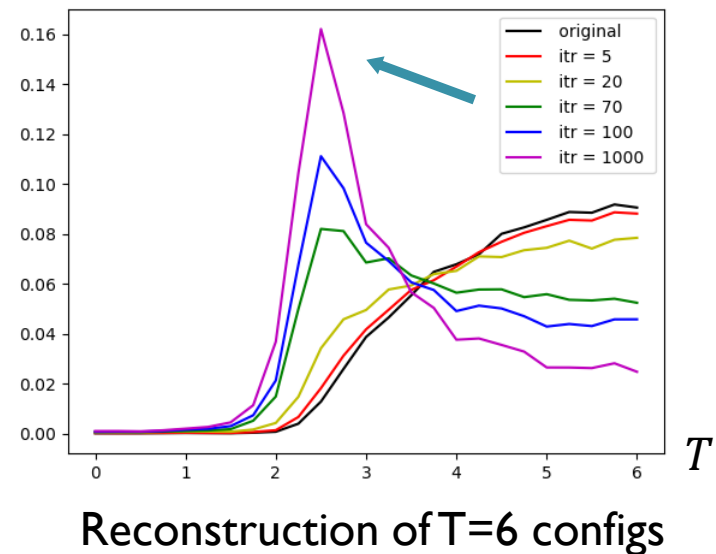
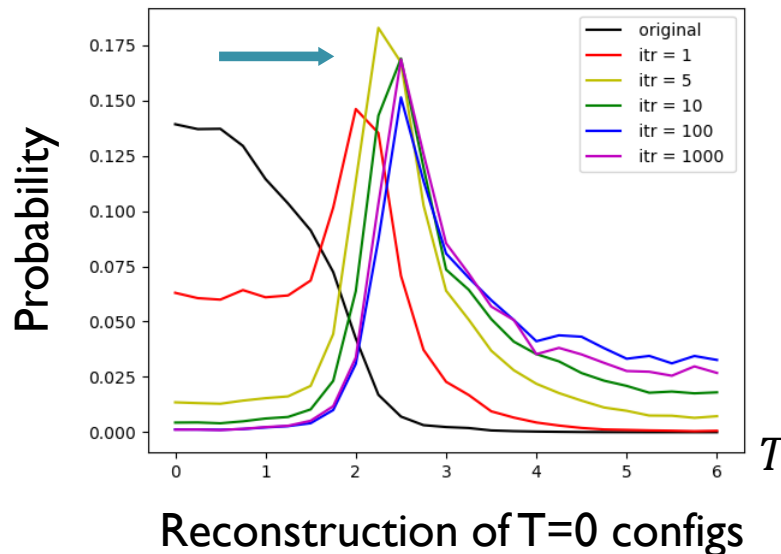


Results: obviously different!

[Iso-SSF-Yokoo, '18]

2d case
at $H=0$

- The RBM flow **approaches the critical point**, while goes away from $T = 0, \infty$. It's the **opposite direction** to the RG flow!

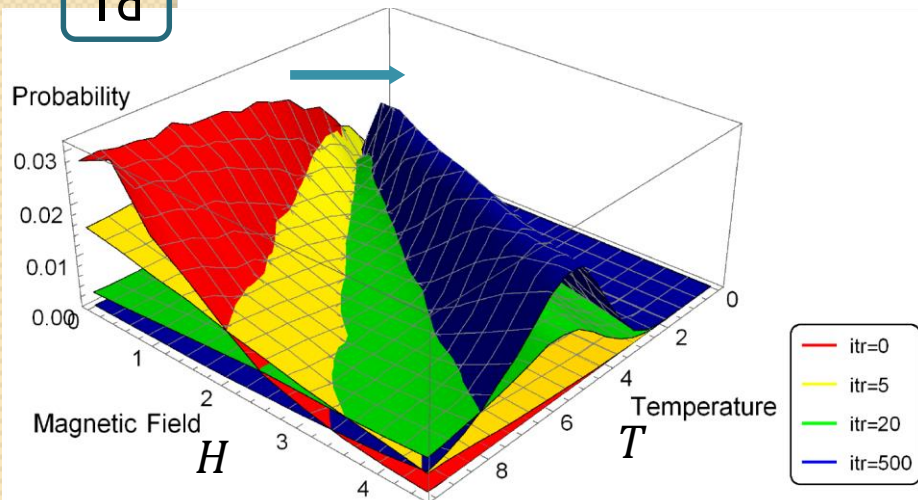


- Data: configs in 10×10 lattice, 1000 configs at each $T=0, 0.25, \dots, 6, H=0$. (Same results when $T=0, 0.25, \dots, 10, \infty$ / $T=0, 0.25, \dots, 2$ and $4, 4.25, \dots, 6$.)
- RBM: $n_v = 100, n_h \leq n_v$, learning rate = 0.1, epoch = 5000

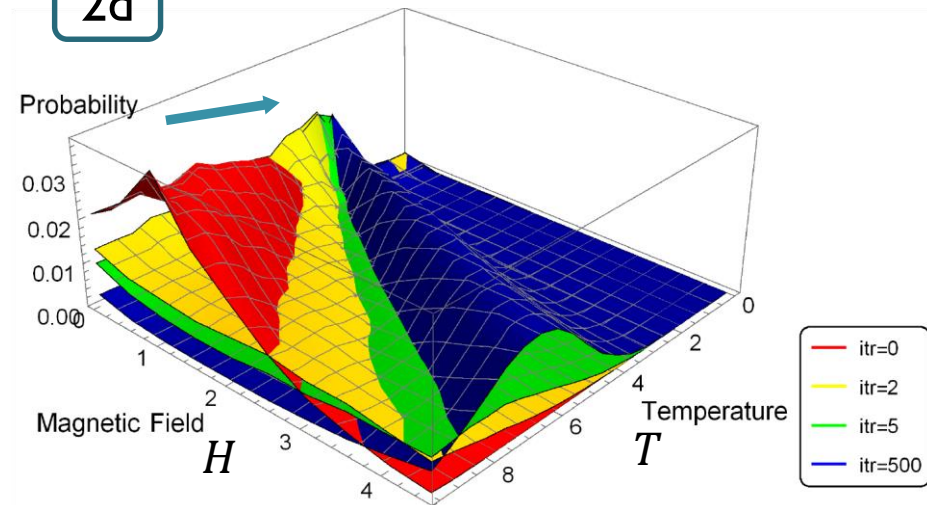
$n_h = 81$

- In 1d and 2d Ising models including $H \neq 0$ region:
 - The **RBM flow** approaches the **fixed points** in (T, H) space. Wherever a start point is, the flow arrives at the *same* points.
 - But they are **different** from the **RG flow** and its fixed points.

1d



2d



- Data: configs in 100 (1d) or 10x10 (2d) lattice, 1000 configs at each (T, H) , where $T=0, 0.5, \dots, 9.5$ and $H=0, 0.5, \dots, 4.5$.
- RBM: $n_v = 100, n_h \leq 16$, learning rate = 0.001, epoch = 10000

$n_h = 9$



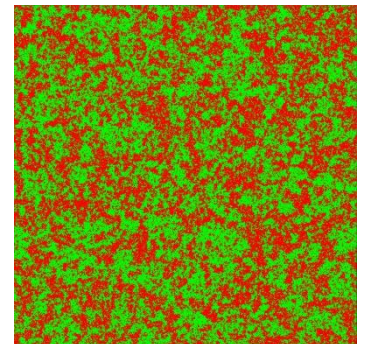
Discussions on our results

RBM flow has fixed points!

- This is (perhaps the only) similarity to **RG flow**.
- The fixed points are in the space of physical quantities (T, H) , not that of configurations.
- Along **RBM flow** the extracted features are emphasized, then its fixed points should be the “**features**” of learning data.
- In 2d case at $H=0$, fixed points exist at the same point.
- But the flows go in the opposite directions.
(stable pt in RBM flow = unstable pt in RG flow)
- What is the “feature” extracted by the RBM?
It is probably the **scale invariance**...?

$$T = T_c$$

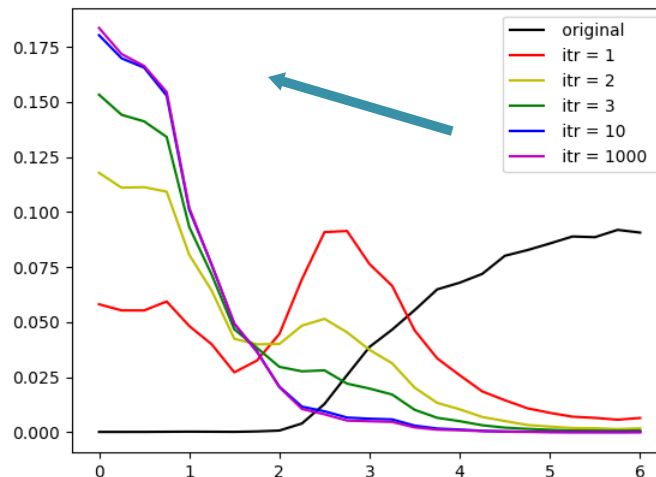
proposal



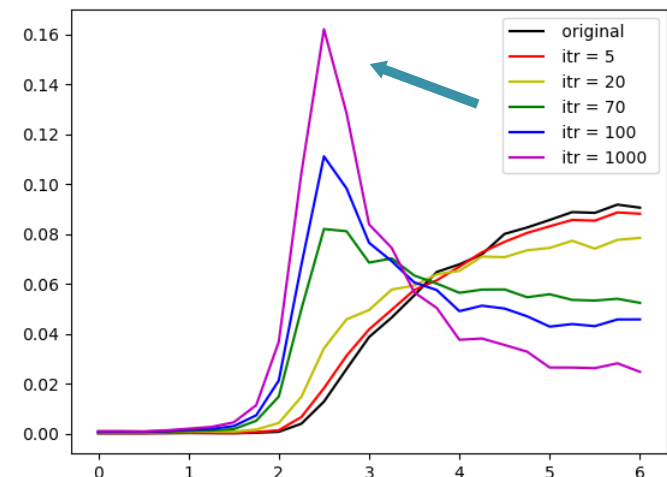
Some evidence for scale invariance

➤ Let us compare the two kinds of RBM by analyzing the **RBM flows** and their **weights**. [Iso-SSF-Yokoo, '18]

- One is the RBM trained by configs at only low temps.
- The other is the RBM learning various temps large scale
 $T = 0, 0.25, \dots, 6$ (and $H=0$).



RBM learning only $T=0$



RBM learning $T=0, \dots, 6$

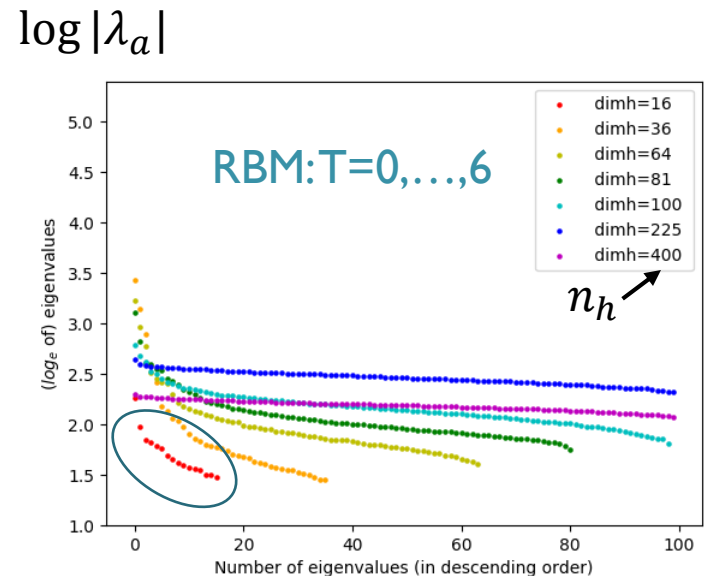
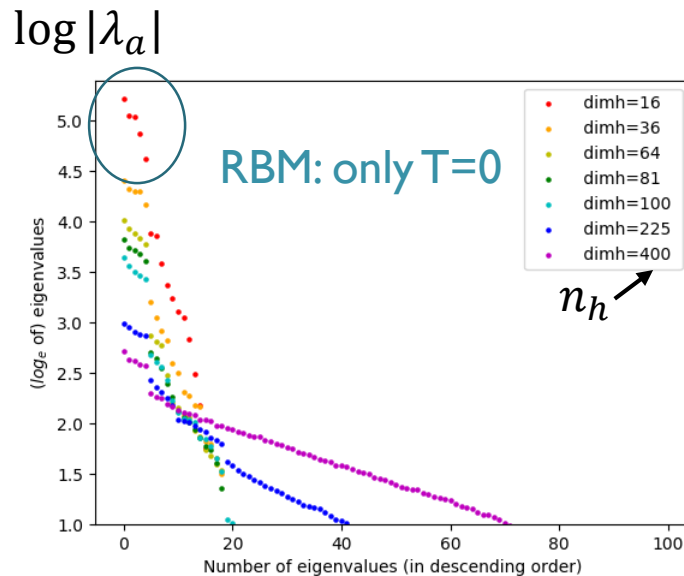
independent from basis of hidden neurons

➤ Eigenvalues of weights $\sum_a w_{ia} w_{ja}$

$$ww^T u_a = \lambda_a u_a$$

- If the RBM learns configs at only low temps, **only a few** (~ 5) eigenvalues are especially large.
- If the RBM learns configs at $T = 0, 0.25, \dots, 6$ (including high temp) **all the eigenvalues** have similar values.

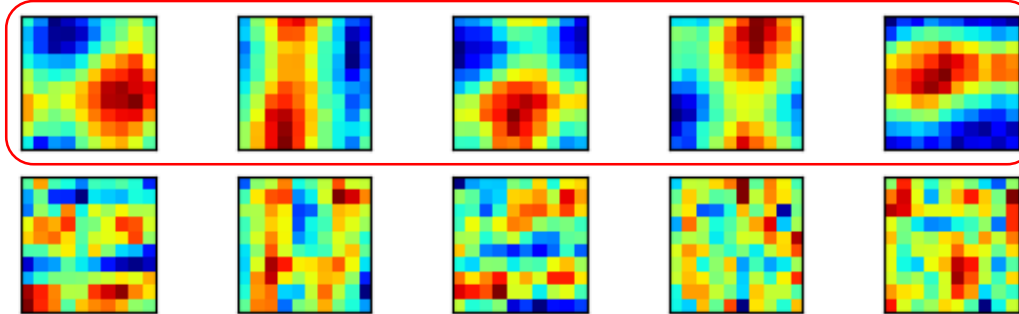
This may be because many hidden neurons are needed to learn configs at various temps (= various scales).



➤ Eigenvectors of ww^T

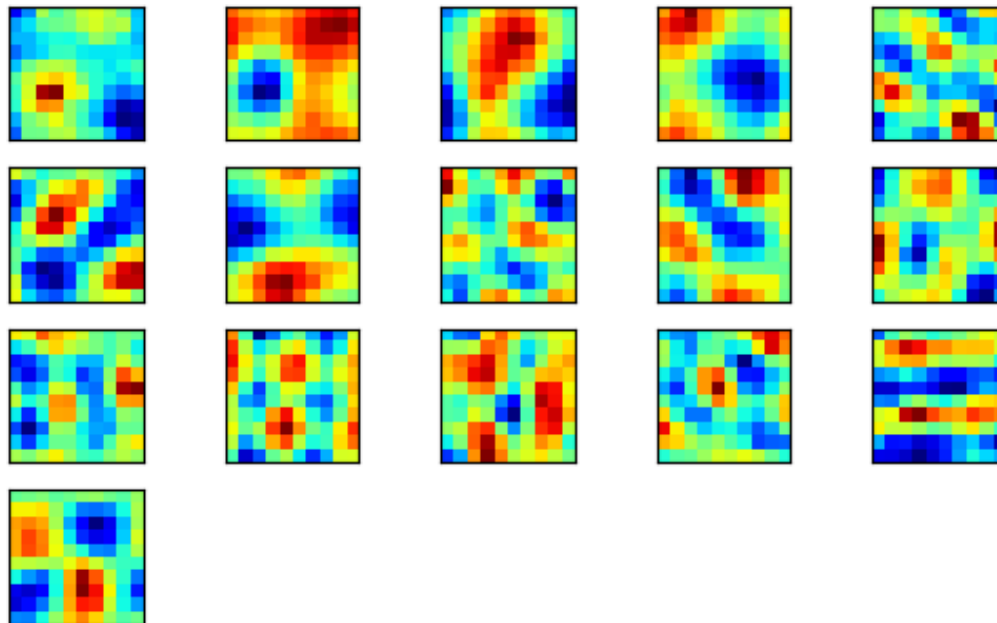
$$ww^T u_a = \lambda_a u_a$$

- RBM learning only **low temps** ($T = 0, \dots, 2, n_h = 16$)



Configs with **large scale** have large eigenvalues.

- RBM learning **various temps** ($T = 0, \dots, 6, n_h = 16$)



Configs with **various scales** have similar eigenvalues!

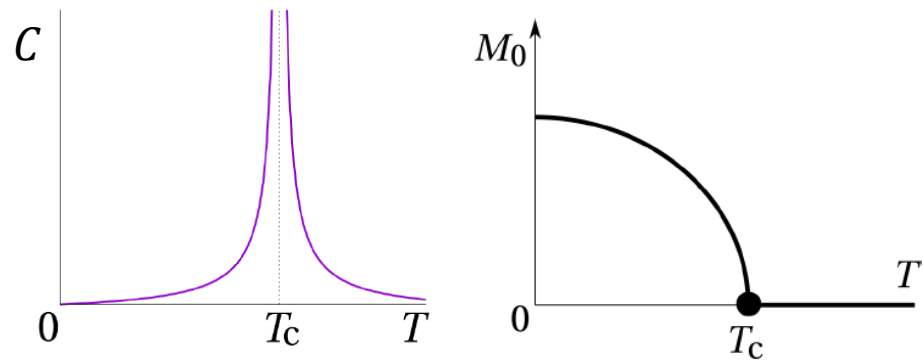
↓
All of them appears in reconstructed images.

↓
Scale invariance...?

General property of fixed points?

- Scale invariance is not a unique choice for “feature”.
- Configs around $T = T_c$ also show the critical behavior of **thermodynamic quantities** (specific heat, magnetization, ...).

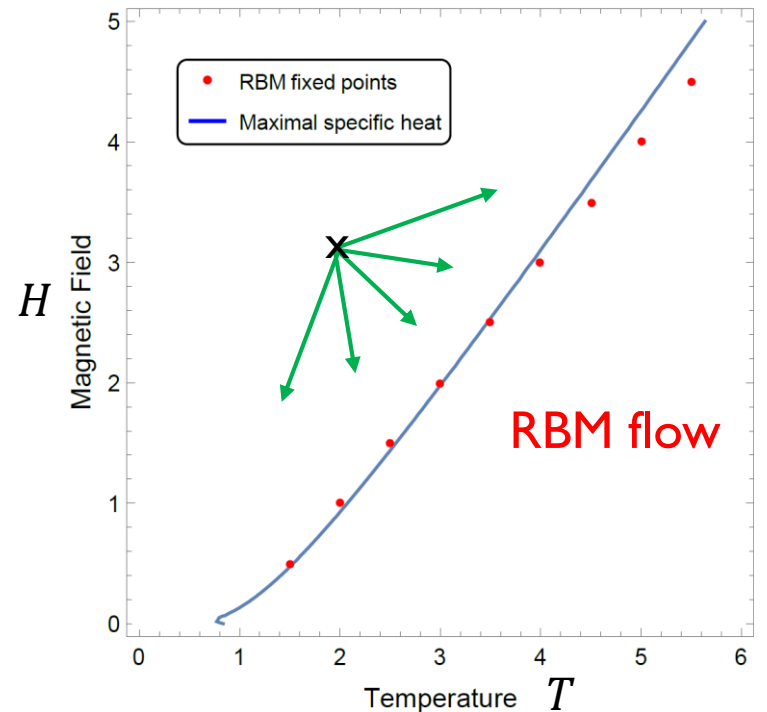
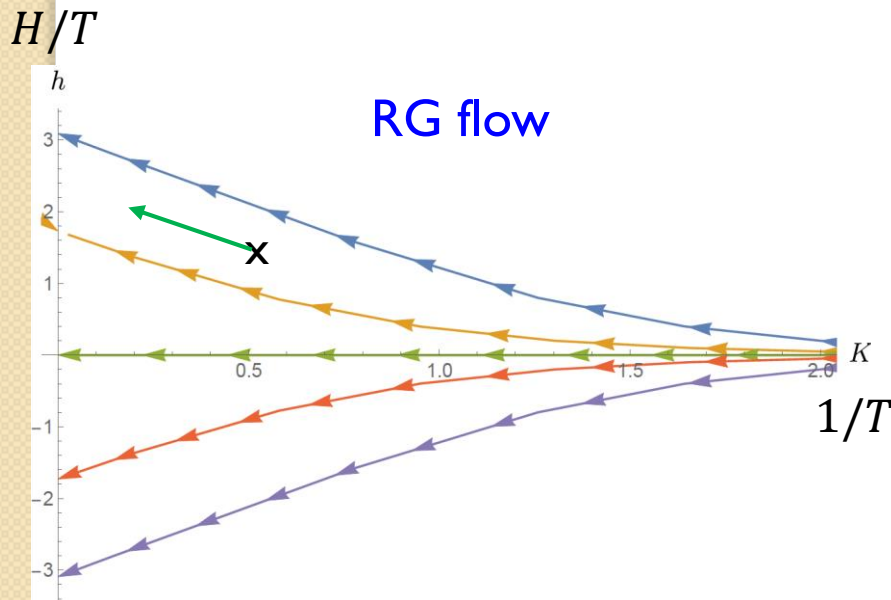
2nd order
phase transition
(at $H=0$)



- Let us study the relation of **RBM flow** and thermodynamics. This gives us further understanding on its behavior.
- Then RBM learning $H \neq 0$ configs show a clear difference from **RG flow** and a close relation to **thermodynamics**.

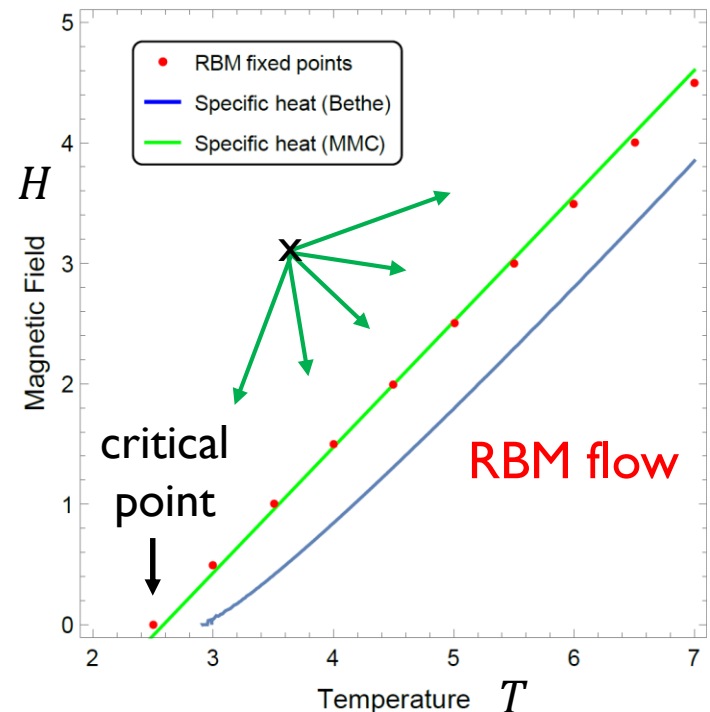
- In **1d Ising model**, we can obtain the exact solutions of RG flow and thermodynamic quantities (even in $H \neq 0$).
- **RG flow** goes in a unique direction. The fixed points are at $(T, H) = (0, 0), (0, \infty), (\infty, *)$. [SSF-Giataganas, '18]
- **RBM flow** approaches to aligned points, so the direction is *not* unique. These fixed points can be fit very well by (local) **maximal specific heat**.

completely different!



- In 2d model we cannot get the exact solutions in $H \neq 0$. Then we use the **Bethe approximation** for analytic calculation and numerical calculation using **Monte Carlo simulation**.
- **RG flow** has the critical fixed point only at $H=0$.
- **RBM flow** behaves similarly to 1d case: [SSF-Giataganas, '18]
It approaches the aligned points (= fixed points).
- The fixed points are coincident *again* with local maximum of **specific heat** $(\partial C / \partial T)_H = 0$.
- It includes the critical point, so the **maximal specific heat** is its suitable generalization.
- This should be the “**feature**”.

more
general
proposal



RBM can learn thermodynamics?

- It seems strange because the **specific heat** $C = \partial E / \partial T$ cannot be directly measured in the input configurations.

- If the RBM can, it must use wisely the “**energy**” function

$$E(\{v_i\}, \{h_a\}) = \sum_{i,a} v_i w_{ia} h_a + \sum_a b_a h_a + \sum_i c_i v_i$$

$$p(\{h_a\}) = \sum_{\{v_i\}} \frac{e^{-E(\{v_i\}, \{h_a\})}}{\mathcal{Z}}$$

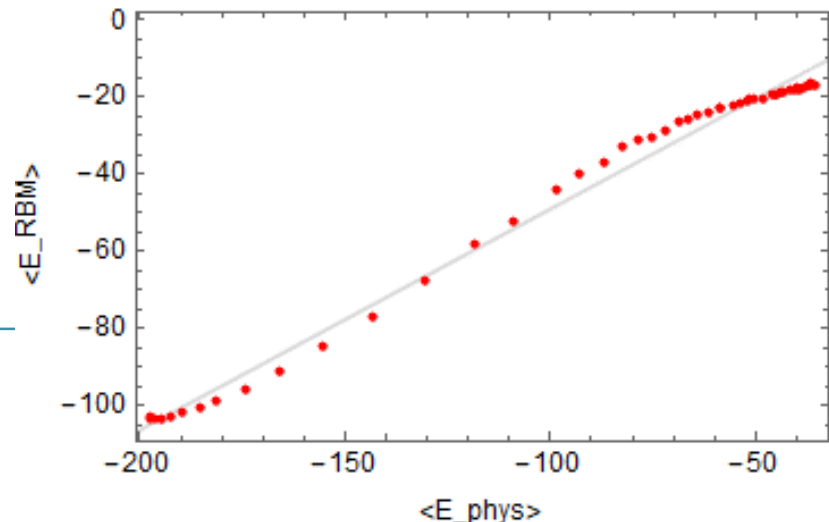
function of weights and biases in Boltzmann distribution

- This “**RBM energy**” seems correlated with **physical energy**, but *not* coincident.

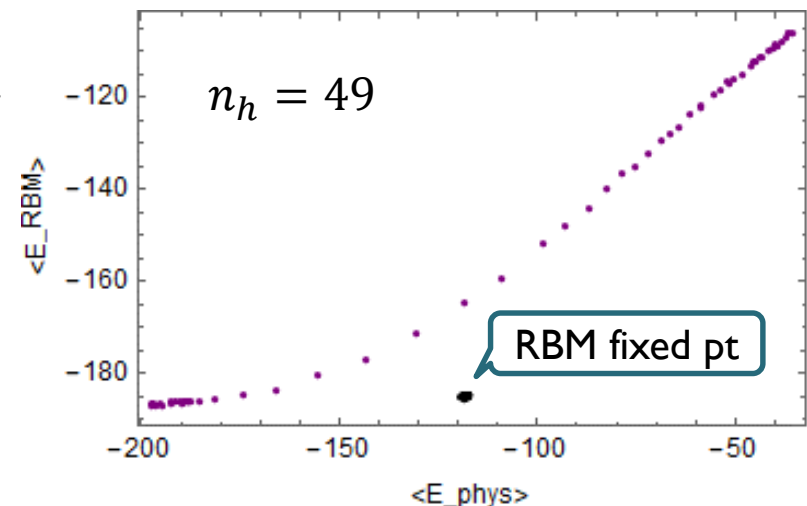
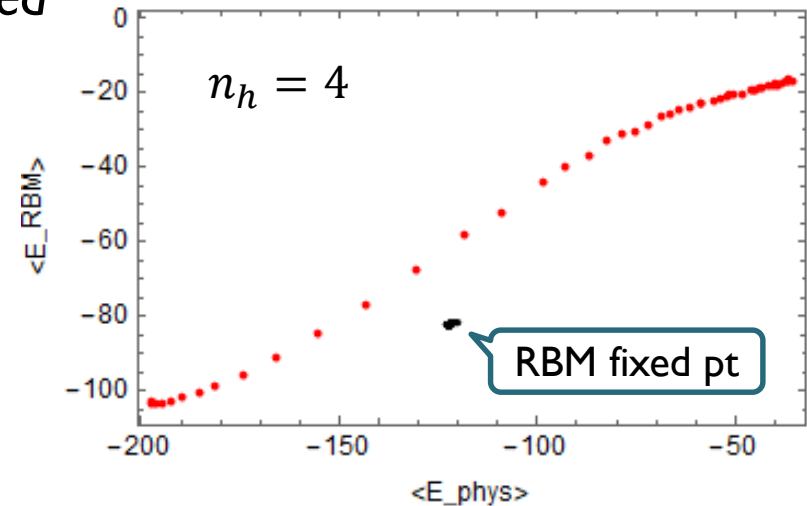
Hamiltonian

$$p \sim e^{-E/T_c}$$

- Data: 2d configs at $T = T_c, H = 0$.
- RBM: $n_v = 100, n_h = 4$



- The relation of **RBM energy** and **physical energy** should be clarified to understand the feature extraction further.
- This relation is easily *changed* by details of training. (e.g., n_h , learning epoch, ...)
- Nevertheless, **RBM flows** have the *same* fixed points in (T, H) space and with *similar* **physical energy**, corresponding to “**feature**”.
- So far I cannot grasp what is essential here. This is an important future work.



Summary & future directions

- We perform a machine learning of the **RBM** to **extract the features** of spin configurations in **Ising model**.
- We find that the **flow** of reconstructed images by **RBM** has the **fixed points** (=“features”) just as the **RG flow**, but their behaviors are obviously different.
- We propose that the features the RBM grasps should be scale invariance and **maximal specific heat**.
- How the RBM learns **thermodynamics** must be clarified.
 - Relation of “**RBM energy**” and physical energy is an important subject of future works.
 - “**RBM flow**” may be related to the way of human recognition...